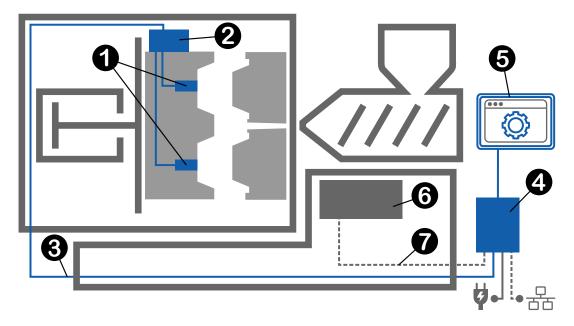


### datasheet DM-qode Gen1

## 1. system description

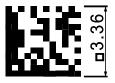
The DynamicMold® allows the application of individual markings on plastic parts, directly during the injection molding process. A DynamicMold® Insert ① is mounted into each cavity wall. If the insert senses the hot plastic melt during the molding process, a trigger activates the marking process machine-independently. The inserts are connected to the DynamicMold® Controller ②, which can handle up to four inserts, and is permanently mounted on the injection molding tool. The Controller Cable ③ connects the Controller with the DynamicMold® LinQ ④. The LinQ is the control unit of the system and is connected to a local area network (optional) and the electricity. Via the Tablet ⑤ settings can be made and the status of the system can be monitored. A potential-free contact (error switch) ⑦ enables the system status to be passed on, for example to the machine control system ⑥.



#### 2D code marking

This version of the mold insert refers to a 144-pixel code in the format 12 x 12 DataMatrix.

DataMatrix Code	module size	data capacity numbers	data capacity text	version
12 x 12	0.28 mm	10 digits	6 characters	ECC 200



#### code reading

It is a DPM code (direct part marking – based on ISO/IEC 16022:2006 and ISO/IEC TR 24720:2008). Common code reader cameras with adapted lighting are suitable to read the code.



### DynamicMold® Software

The DynamicMold® software controls the correct mapping of the marking. Two use cases are supported:

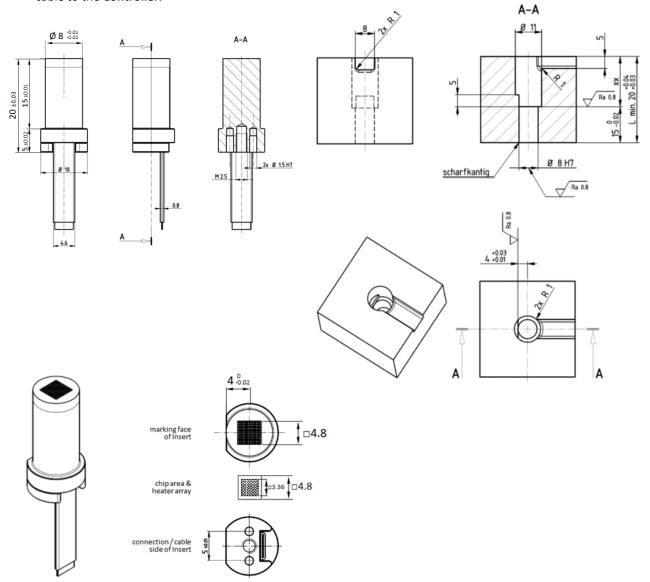
- **front-end mode**: allows the customer to configure code allocation via the tablet. The operator has full control over the marking process.
- **local-remote mode**: the LinQ receives the codes from a third-party system (e.g. MES) via OPC-UA. The latter is responsible for assigning the code.

#### DynamicMold® installation instructions

## DynamicMold® Insert

The DynamicMold® Insert consists of a steel housing with a ceramic chip embedded on the front and a ribbon cable for connection to the DynamicMold® Controller. The mold insert *must not* be processed mechanically! The cable *must not* be shortened!

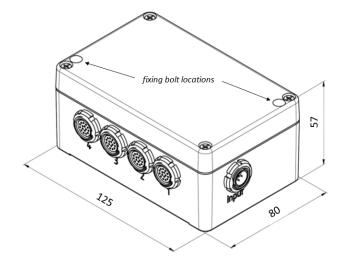
The mold insert is installed from the mold tool exterior. A machined recess is required for this, as shown in the illustration. A spacer is necessary to compensate for the distance between the back of the mold insert and the adjacent plate. The spacer is *not* included in the delivery. A cable duct must be installed in the tool to route the cable to the **Controller.** 





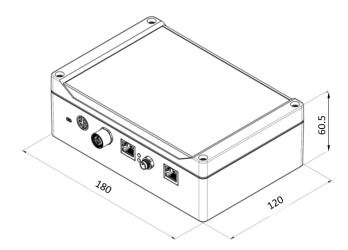
### DynamicMold® Controller

The DynamicMold® Controller is the control unit for DynamicMold® Inserts and is mounted permanently on the injection molding tool. Two fixing bolts are at the edges of the Controller housing. Up to four Inserts can be connected to the Controller. If the tool temperature is over 60°C, and spacers must be used between the tool and the Controller.



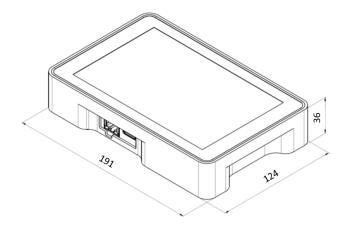
#### DynamicMold® LinQ

The DynamicMold® LinQ is the central control unit and the interface between the Controller and the company network (via OPC UA) or the injection molding machine. The LinQ is connected to the controller via a cable but remains outside the machine. Installation can be done directly on the machine using the integrated magnets. The necessary settings can be made via the tablet, which can be connected to the LinQ. A potential-free contact (error switch) can be used to report any errors that occur in the DM-qode Gen1 system.



#### **Tablet**

The marking process is started via the **Tablet's** user interface and the marking parameters are adjusted to optimize the code quality. The USB interface on the **Tablet** enables software updates and data export.





# 2. technical specifications

# process data

version	DM-qode Gen1
process	plastic injection molding; on demand: thermoforming, blow-molding (stretch, extrusion)
injection molding machine	machine independent
triggering	self-triggering (internal temperature sensor triggers marking)
minimal cycle time	3 s (including ca. 0.1 s marking duration)

# DynamicMold® Insert

dimensions	frontal Ø 8 mm, length 20 mm (see CAD data)
working temperature	max 80°C (molding tool body), max 300°C (molding compound)
pressure stability	up to 2000 bar
cable length	ca. 750 mm
weight	40 g

# DynamicMold® LinQ

dimensions	ca. 180 mm x 120 mm x 61 mm (see CAD data)	
temperature	0-40°C	
humidity	not condensing	
IP rating	IP40	
power supply	24V/5A (power supply included for 100-240VAC 50Hz/60Hz, 1.4A-0.7A)	
connections	power supply: 24V DIN 4 Pin (cable included) network: RJ45 Ethernet tablet connection: RJ45 Ethernet with PoE (cable included) DynamicMold® Controller: M12 (cable included) Error switch: M8 male 3PIN, max. 3m	
connectivity	OPC UA	
mounting	magnetically	
weight	1.05 kg <b>LinQ</b> ca. 800 g power supply ca. 400 g – 1.2 kg Controller Cable (depending on length)	



### **DynamicMold® Controller**

dimensions	ca. 125 mm x 80 mm x 57 mm (see CAD data)
surface temperature injection molding tool	0-60°C up to 80°C using seperators
humidity	not condensing
IP rating	IP65
connections	1-4 DM-qode Insert connectors, DynamicMold® LinQ input port
weight	530 g

#### **Tablet**

dimensions	ca. 191 mm x 36 mm x 124 mm (see CAD data)
temperature	0-40°C
humidity	not condensing
IP rating	front IP65, plug outlet IP40
connections	Ethernet with PoE, USB 2.0
mounting	magnetically
weight	1.15 kg

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document version: Rev01

This document has been prepared carefully and to the best of our knowledge. Chapter 1 is purely descriptive and therefore non-binding.

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